

DYNAMICS OF REACTION SYSTEMS

Anne Shiu

University of Chicago

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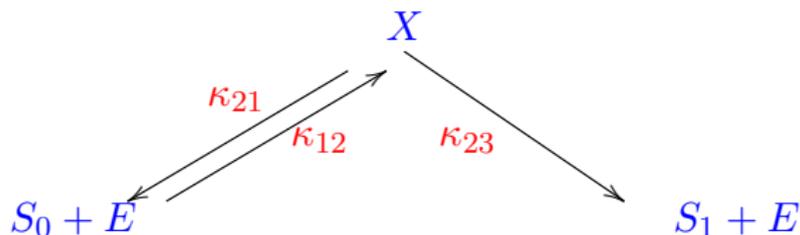
OUTLINE OF TALK

- ▶ Chemical reaction systems
 - ▶ Convergence properties
 - ▶ Long-term dynamics (persistence)
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Main message:

Algebraic and combinatorial techniques are complementary to existing dynamical systems approaches.

CHEMICAL REACTION NETWORKS

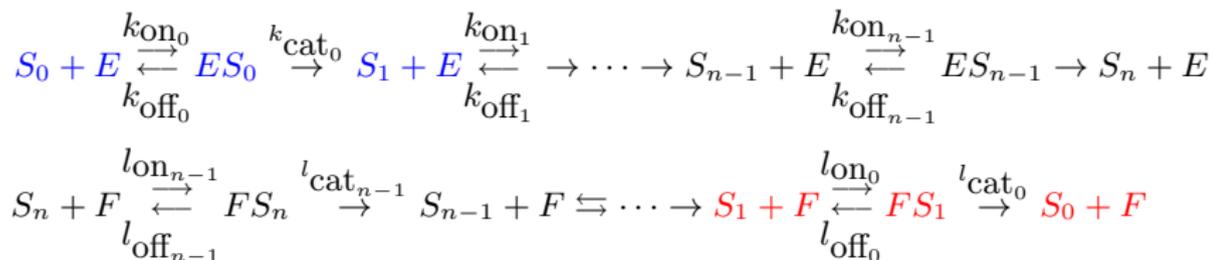


This *chemical reaction network* has:

- ▶ $r = 3$ **reactions** (with *reaction rate constants* κ_{ij}) among the ...
- ▶ $n = 3$ **complexes** $S_0 + E$, X , and $S_1 + E$ which are comprised of ...
- ▶ $s = 4$ **species** S_0 , S_1 , E , and X .

THE MULTISITE PHOSPHORYLATION NETWORK

The n -site (sequential and distributive) phosphorylation network is:



Given initial concentrations,
how do the concentrations of S_0 , S_1 , \dots , E , F evolve in time?

$$c(t) = (c_{S_0}(t), c_{S_1}(t), \dots, c_E(t), c_F(t))$$

2-SITE PHOSPHORYLATION IN AN OSCILLATOR

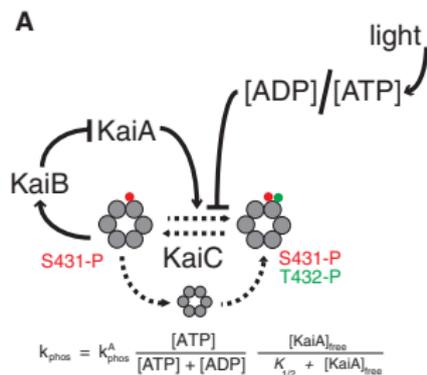


Fig. 4. A mathematical model of the KaiABC oscillator predicts entrainment by varying the ATP/ADP ratio. **(A)** Schematic of a mathematical model for nucleotide-driven entrainment of the KaiABC oscillator. Oscillations occur because the Ser⁴³¹-phosphorylated form of KaiC promotes its own production from KaiC phosphorylated at both Ser⁴³¹ and Thr⁴³² through a double-negative feedback loop involving sequestration of KaiA.

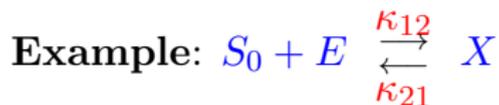
(Figure from Rust, Golden, and O'Shea, Light-Driven Changes in Energy Metabolism Directly Entrain the Cyanobacterial Circadian Oscillator, *Science* 2011).

CHEMICAL REACTION SYSTEMS

Fix a chemical reaction network with s species.

- ▶ Each chemical complex defines a vector $y \in \mathbb{Z}_{\geq 0}^s$
(ex: $S_0 + E$ defines $y_1 = (1, 1, 0)$)
- ▶ (Guldberg and Waage 1864) According to **mass-action kinetics**, the concentration vector $\mathbf{c}(t) = (c_1(t), \dots, c_s(t))$ evolves according to the following differential equations:

$$\frac{d\mathbf{c}}{dt} = \sum_{\substack{y_i \rightarrow y_j \\ \text{is a reaction}}} \kappa_{ij} \mathbf{c}^{y_i} (y_j - y_i)$$



$$\frac{dc_{S_0}}{dt} = -\kappa_{12} c_{S_0} c_E + \kappa_{21} c_X$$

$$\frac{dc_E}{dt} = -\kappa_{12} c_{S_0} c_E + \kappa_{21} c_X$$

$$\frac{dc_X}{dt} = \kappa_{12} c_{S_0} c_E - \kappa_{21} c_X$$

MOTIVATION

Question: Is the n -site phosphorylation network...

1. *bistable*?

(Answer due to Wang and Sontag 2008: only for $n \geq 2$.)

2. *convergent to a unique steady state*? (Only for $n = 1$.)

3. *persistent*: does every species concentration $c_i(t)$ remain away from 0? (Yes.)

Rest of talk:

How can we answer questions 2 and 3 for arbitrary networks?

COMPLEX-BALANCED SYSTEMS

Idea: amount produced of each complex at steady state = amount consumed; a class of systems that converge to a unique steady state.

- Rewrite the mass-action ODEs as:

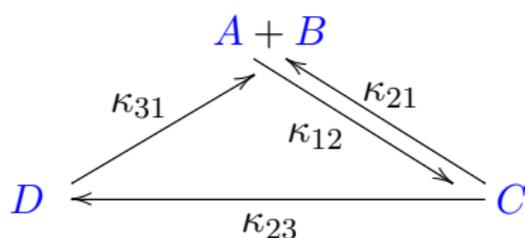
$$\begin{aligned}\frac{dc}{dt} &= \sum_{\substack{y_i \rightarrow y_j \\ \text{is a reaction}}} \kappa_{ij} (y_j - y_i) c^{y_i} \\ &= (c^{\tilde{y}_1}, \dots, c^{\tilde{y}_n}) \cdot A_\kappa \cdot (\tilde{y}_{ij})_{i=1\dots n, j=1\dots s} \\ &\quad \mathbb{R}^{\#\text{species}} \rightarrow \mathbb{R}^n \rightarrow \mathbb{R}^n \rightarrow \mathbb{R}^{\#\text{species}}\end{aligned}$$

where $\tilde{y}_1, \dots, \tilde{y}_n$ are the n complexes, s is the number of species, and A_κ is the *Laplacian matrix* of the network.

- (definition, [Horn and Jackson 1972](#)) A mass-action kinetics system is a **complex-balanced system** if there exists a steady state $c^* \in \mathbb{R}_{>0}^s$ with $((c^*)^{\tilde{y}_1}, \dots, (c^*)^{\tilde{y}_n}) \cdot A_\kappa = 0$.

LAPLACIAN MATRIX EXAMPLE

For the following “kinetic proofreading” network:



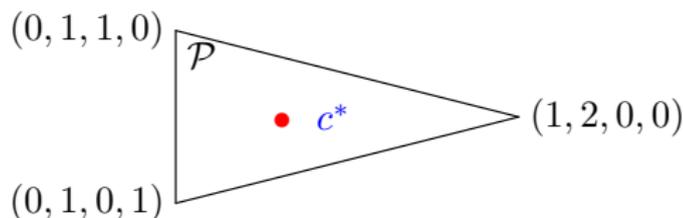
the Laplacian matrix is:

$$A_{\kappa} := \begin{pmatrix} -\kappa_{12} & \kappa_{12} & 0 \\ \kappa_{21} & -\kappa_{21} - \kappa_{23} & \kappa_{23} \\ \kappa_{31} & 0 & -\kappa_{31} \end{pmatrix}.$$

(McKeithan 1995, Sontag 2001)

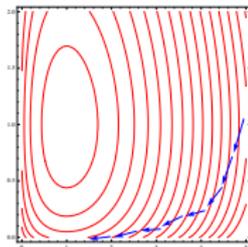
COMPLEX-BALANCED SYSTEMS, CONTINUED

- ▶ **Theorem** (Craciun, Dickenstein, AS, and Sturmfels 2009): A mass-action kinetics system is a **complex-balanced system** if and only if the parameters k_{ij} lie in a certain *toric variety*.
- ▶ **Birch's Theorem** (1963), **Deficiency Zero Theorem** (Horn, Jackson, Feinberg 1970s): For complex-balanced systems, there is a *unique steady state* c^* in the relative interior of each forward-invariant polyhedron \mathcal{P} , called the **Birch point**, and it admits a strict Lyapunov function.
- ▶ Example: “*kinetic proofreading*” model



COMPLEX-BALANCED SYSTEMS: CONVERGENCE?

- ▶ The Lyapunov function $\sum \left(x_i \log \frac{x_i}{c_i^*} - x_i \right)$ is not sufficient to prove global convergence to the Birch point:



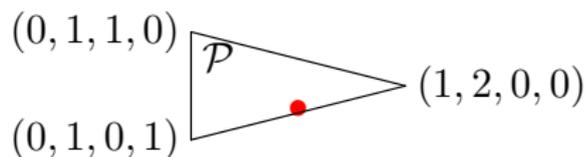
- ▶ **Global Attractor Conjecture** (Horn 1974): *For a complex-balanced system with positive initial condition,*

$$c(t) \rightarrow c^*,$$

for c^ the Birch point of the forward-invariant set \mathcal{P} .*

KNOWN CONVERGENCE RESULTS

- ▶ A *boundary steady state* is a steady state with at least one zero coordinate:



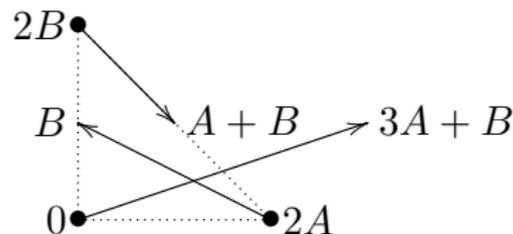
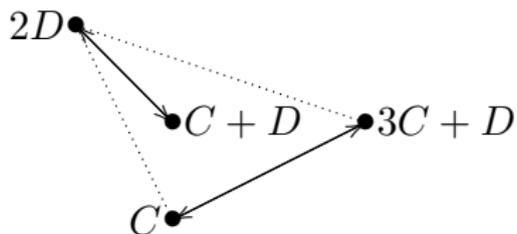
- ▶ **Theorem** (Anderson, Craciun, Dickenstein, Nazarov, Pantea, AS, Sturmfels 2007–2012): The Global Attractor Conjecture holds if *boundary steady states are confined to*:
 - ▶ vertices of \mathcal{P} ,
 - ▶ relative interior points of facets (codim-1 faces) of \mathcal{P} , and
 - ▶ relative interior points of codim-2 faces of \mathcal{P} .
- ▶ **Corollary**: The Global Attractor Conjecture holds for when *the number of species is* ≤ 3 .
- ▶ See also Johnston and Siegel 2011, *siphons* (Angeli, De Leenheer, Sontag,...), and *monotone systems* (Banaji, Hirsch, Smith,...).

NEW RESULT ON CONVERGENCE AND PERSISTENCE

To prove the GAC, it suffices to prove that complex-balanced systems are **persistent**, that is, for all species i and trajectories $c(t)$ with positive initial condition, $\liminf_{t \rightarrow \infty} c_i(t) > 0$. (Smith, Theime)

- ▶ Thus, the GAC generalizes to:

Conjecture (Craciun, Nazarov, Pantea): Every *endotactic* (“inward-pointing”) network is persistent. **Examples:**



- ▶ **Theorem** (Gopalkrishnan, Miller, AS): Every *strongly endotactic* network is persistent. **Example above on right.**

SUMMARY

Chemical reaction systems form a class of dynamical systems arising in systems biology for which methods from *computational algebra and polyhedral geometry* can be harnessed to prove results about the *existence, uniqueness, and stability of steady states*.

THANK YOU.